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CROSSEYE: a CubeSat LEO constellation for plastic litter detection in open sea

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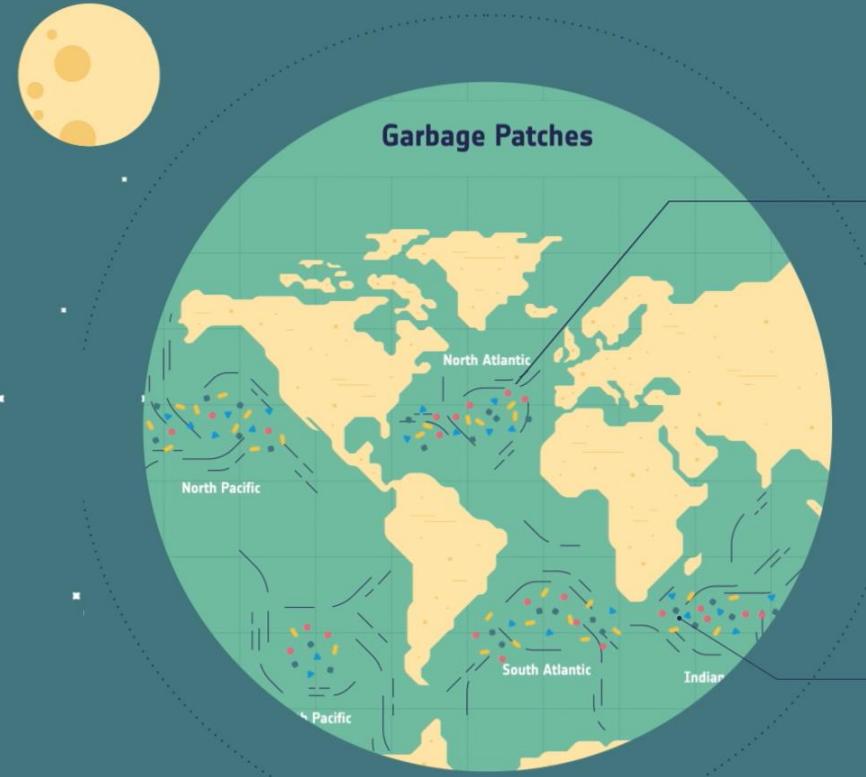
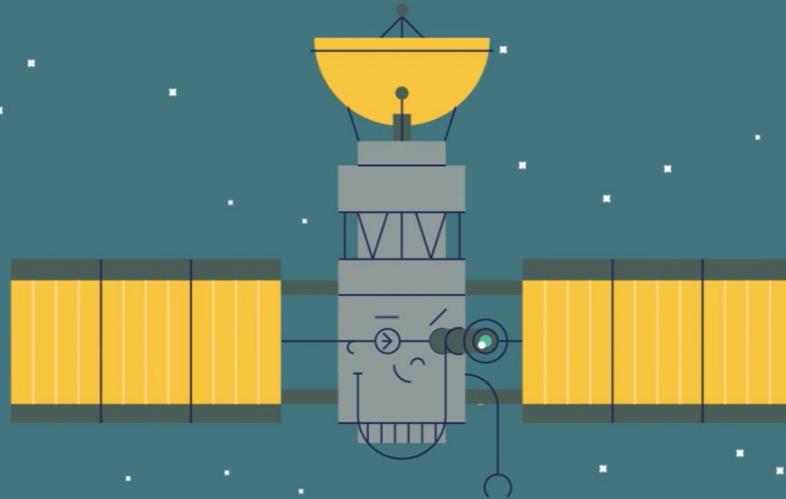
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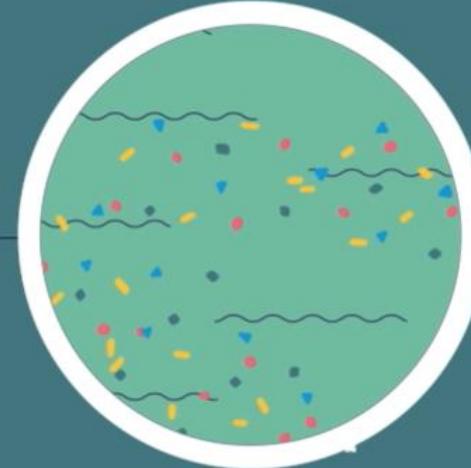
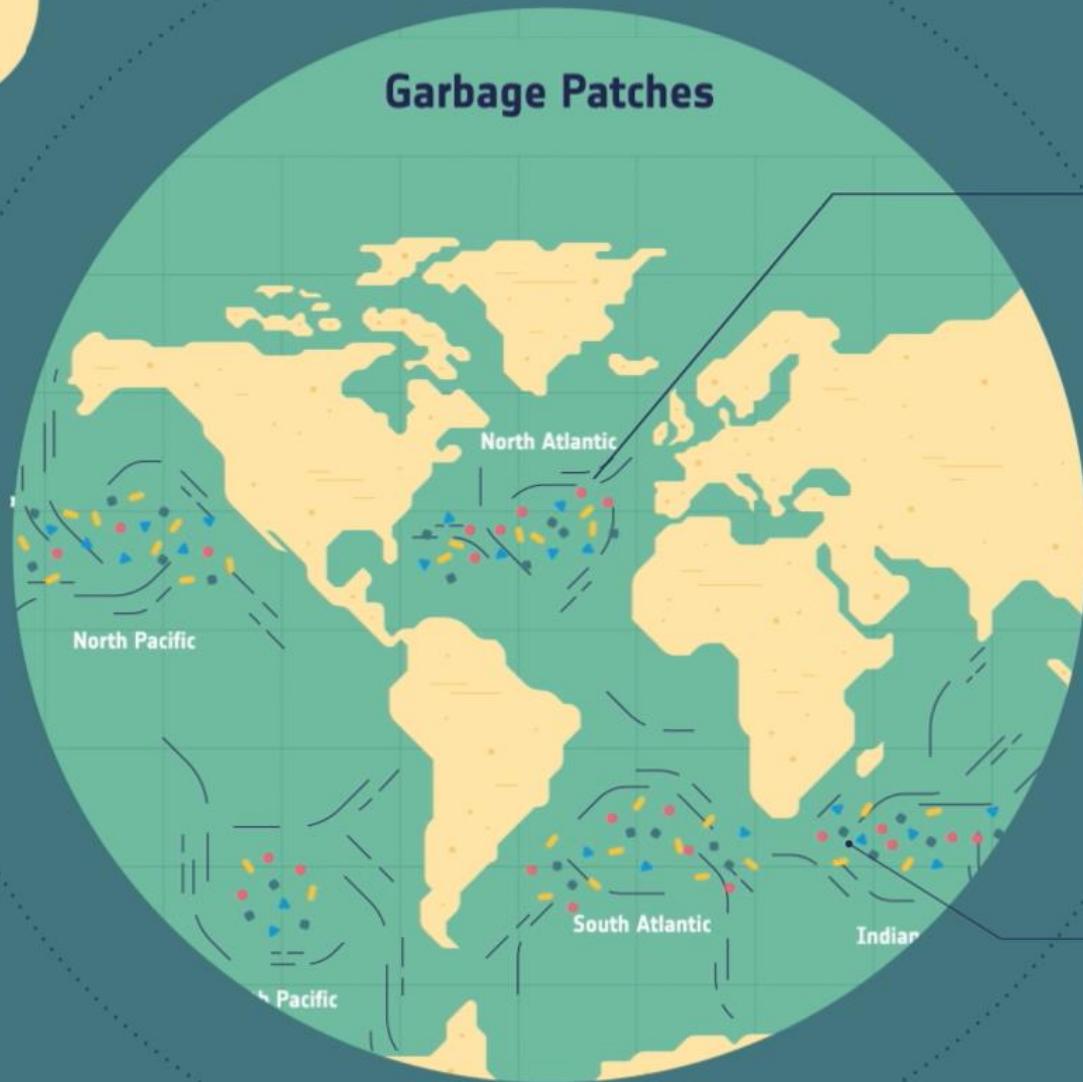
Introduction

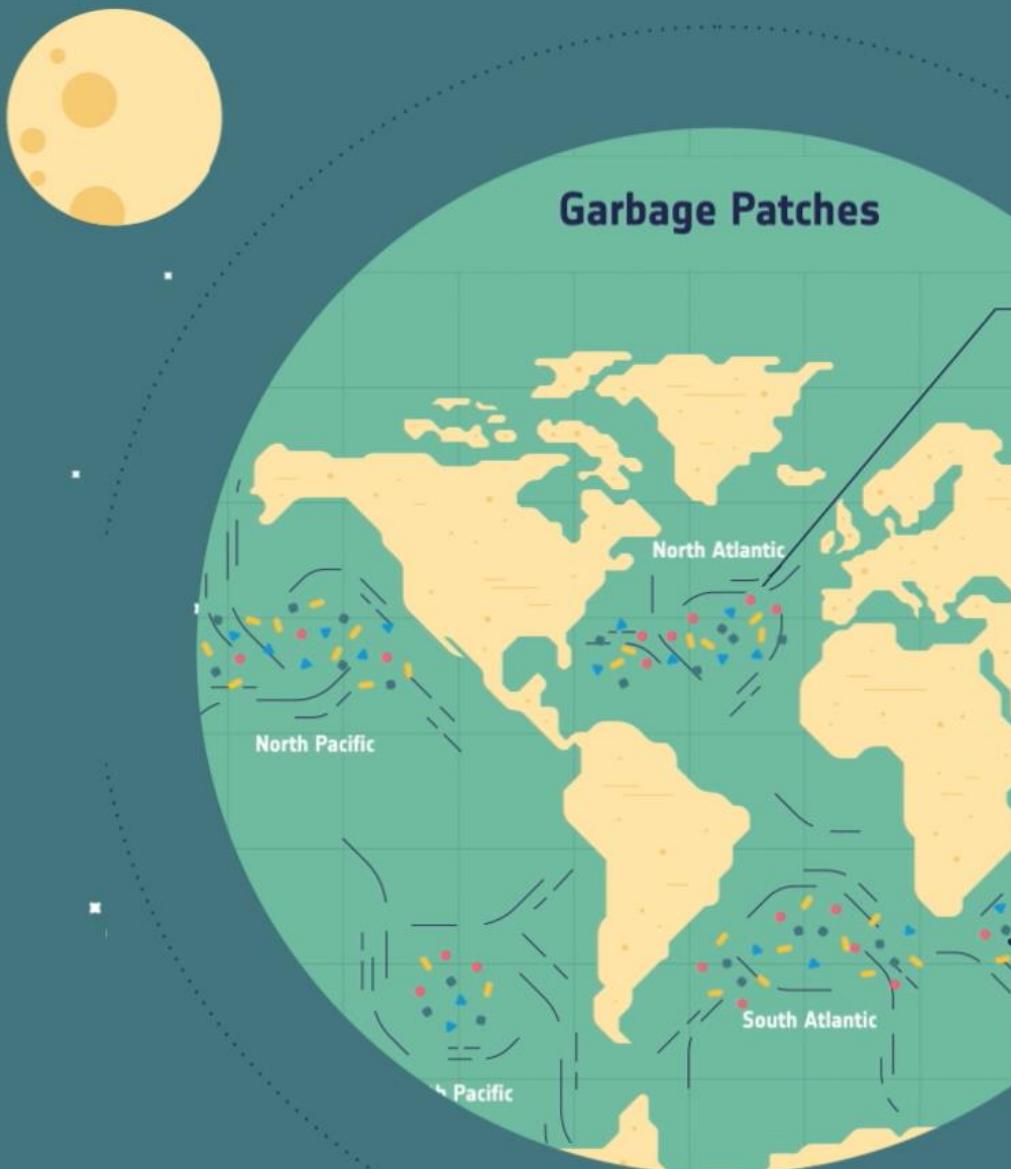
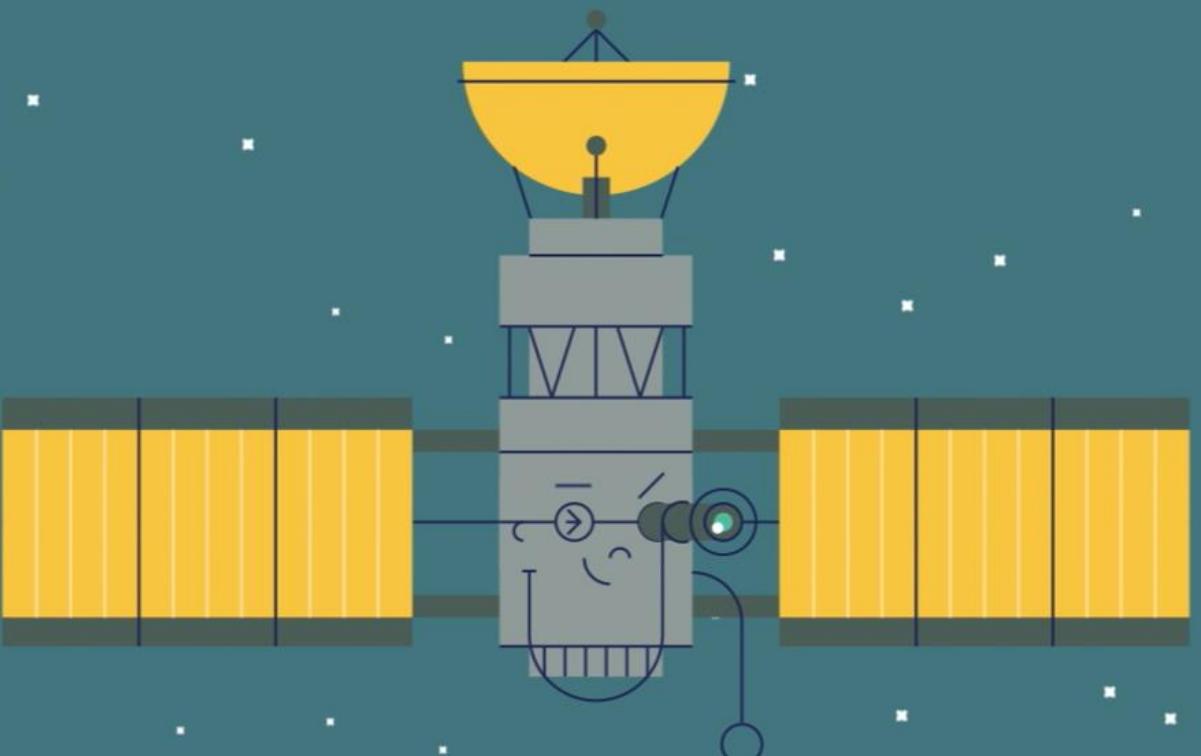
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eesa

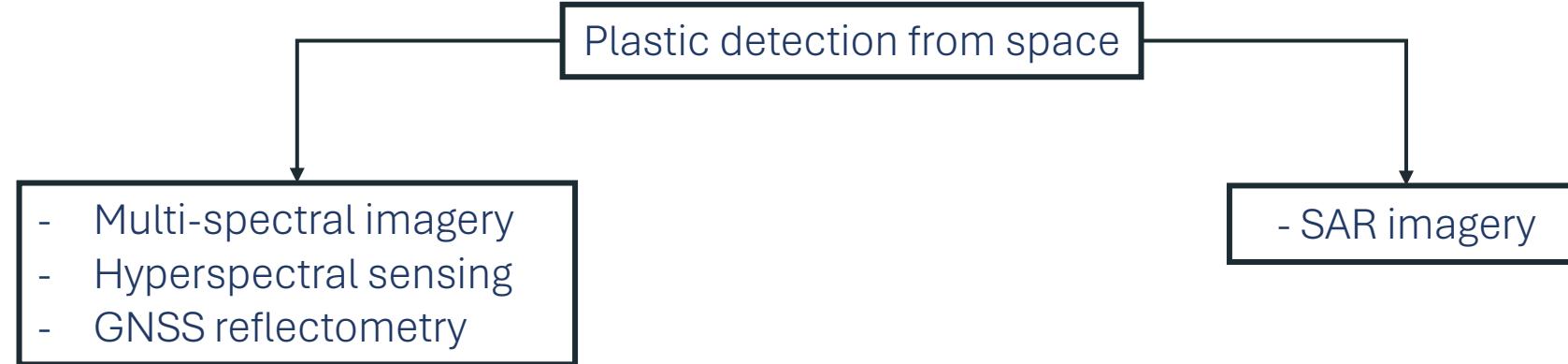








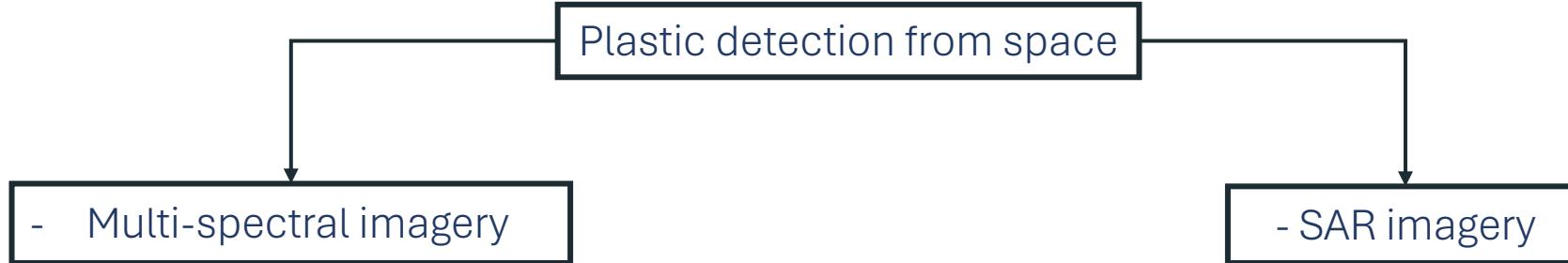
Introduction



- ✓ Good capabilities demonstrated in this field
- ✗ No operational system for global monitoring and detection of plastics with sufficient temporal and spatial coverage
- ✓ Would allow global monitoring of plastic litter at sea
- ✗ Robust approaches for SAR-based plastic detection at sea not available due to the lack of assessed datasets to train and test new procedures on large scales



Introduction



- ✓ Good capabilities demonstrated in this field
- ✓ Would allow global monitoring of plastic litter at sea

CROSSEYE

(Combined in pendulum Remote Observation cubeSat System for icEYE) mission



Mission Objectives

OB1:

- Macroplastic detection in open sea through EO acquisitions

OB2:

- EO/SAR - based innovative measurement principle validation

OB3:

- Development of a database of collected plastic data



Key Parameters

OB1:

- Macroplastic detection in open sea through EO acquisitions

OB2:

- EO/SAR - based innovative measurement principle validation

OB3:

- Development of a database of collected plastic data

KP1:

- 20 m spatial resolution

KP2:

- 6 bands (NDVI, FDI, FAI)

KP3:

- Simultaneous acquisitions (time lag +/- 4 h)

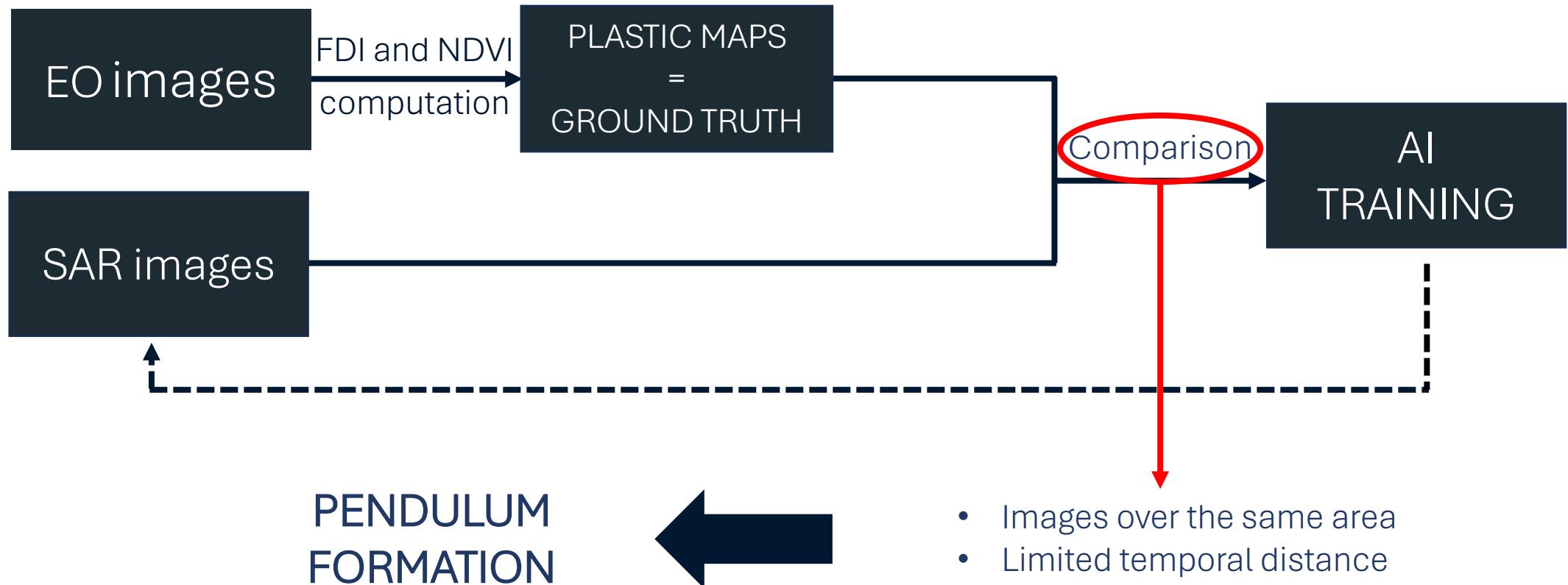


AI detection of marine litter in SAR images – Measurement principle





AI detection of marine litter in SAR images – Measurement principle

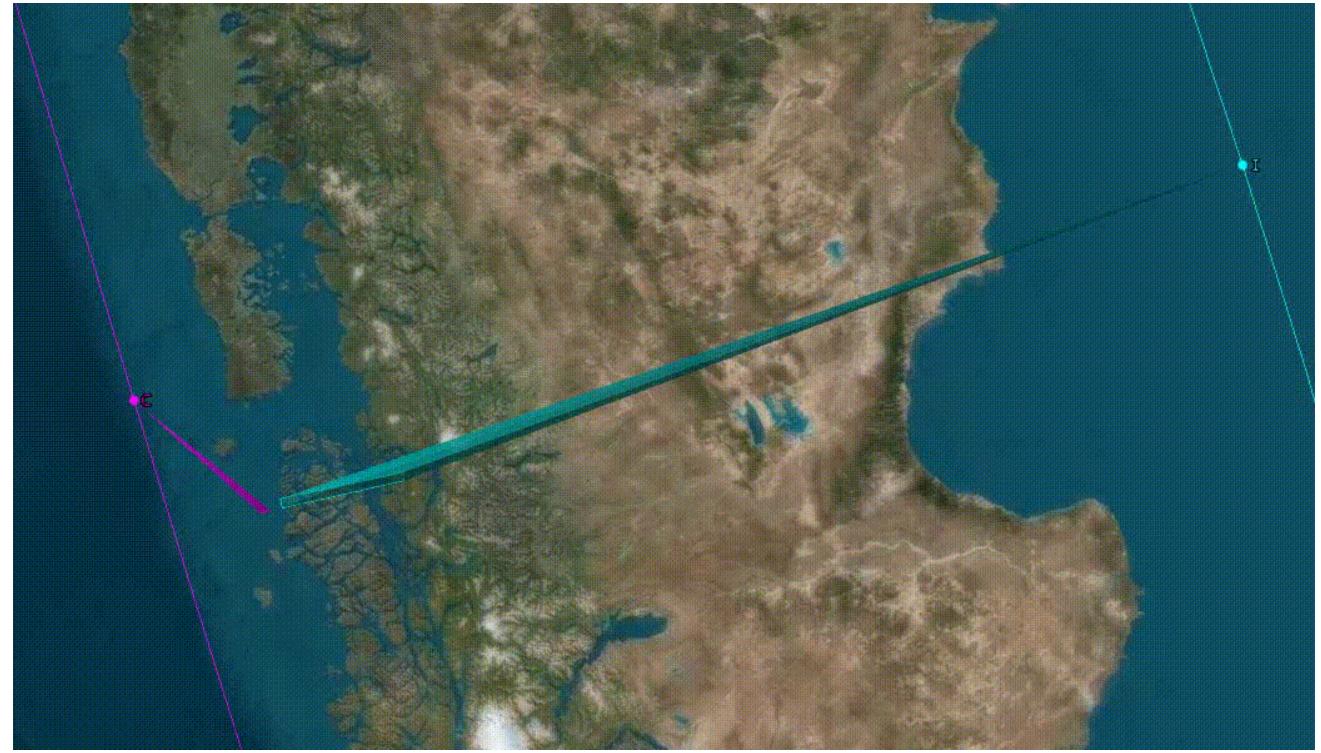
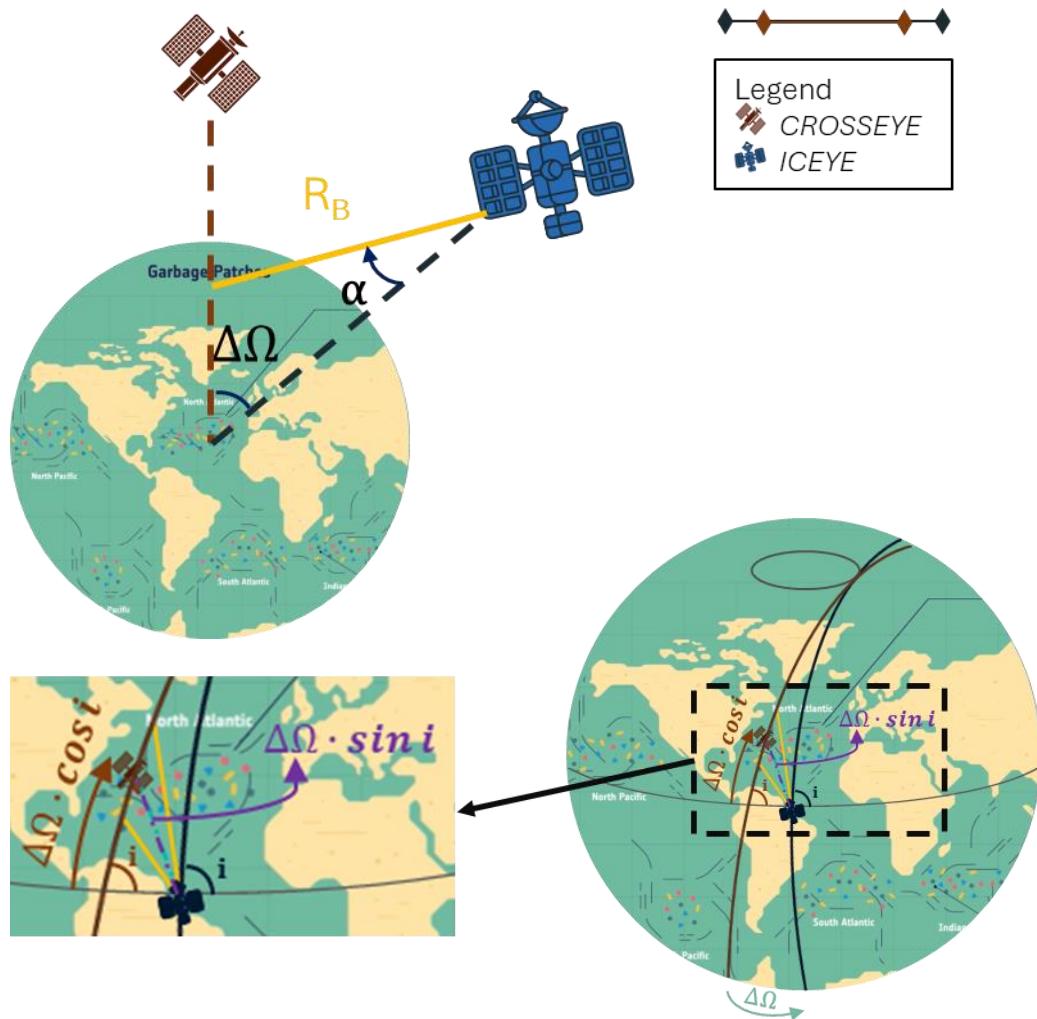




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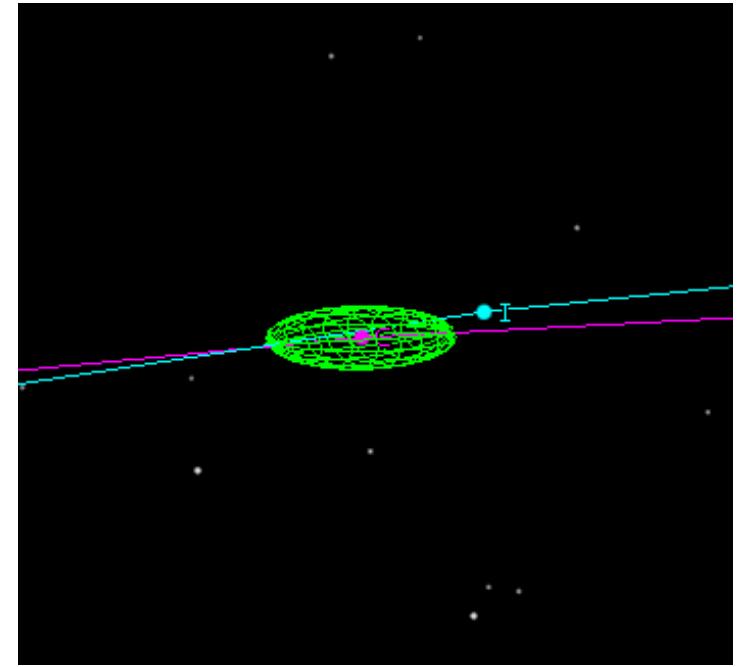
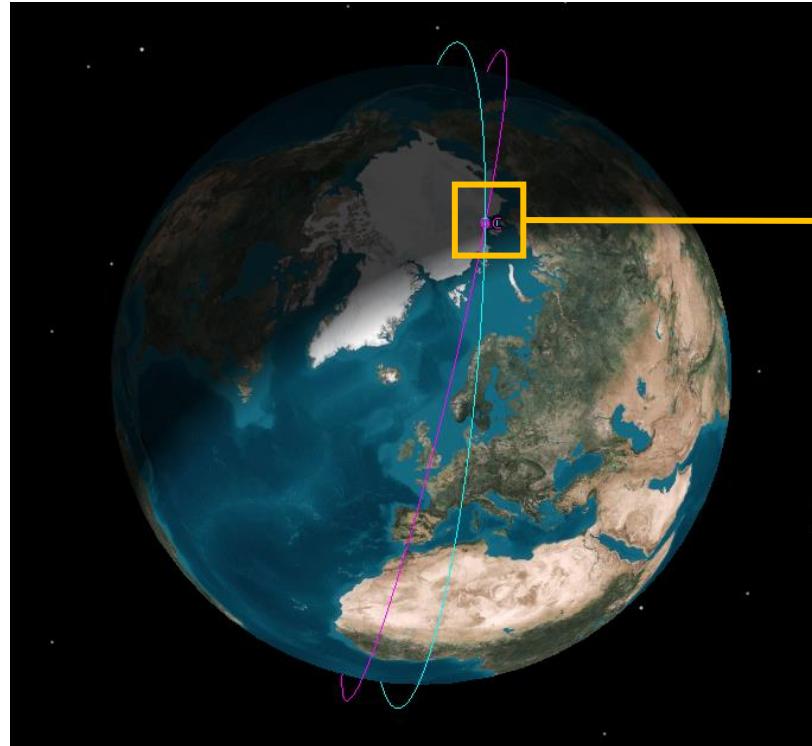
Pendulum

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Safety distance



- Δe provides radial and cross-track separation
- Δv provides along-track separation (~ 16 Km)



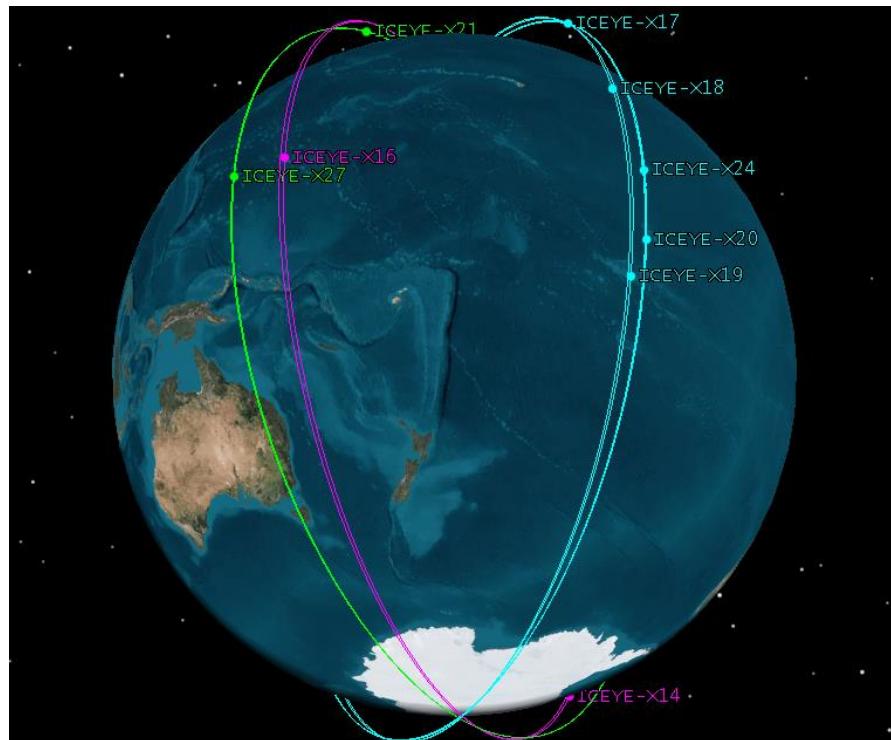
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Constellation

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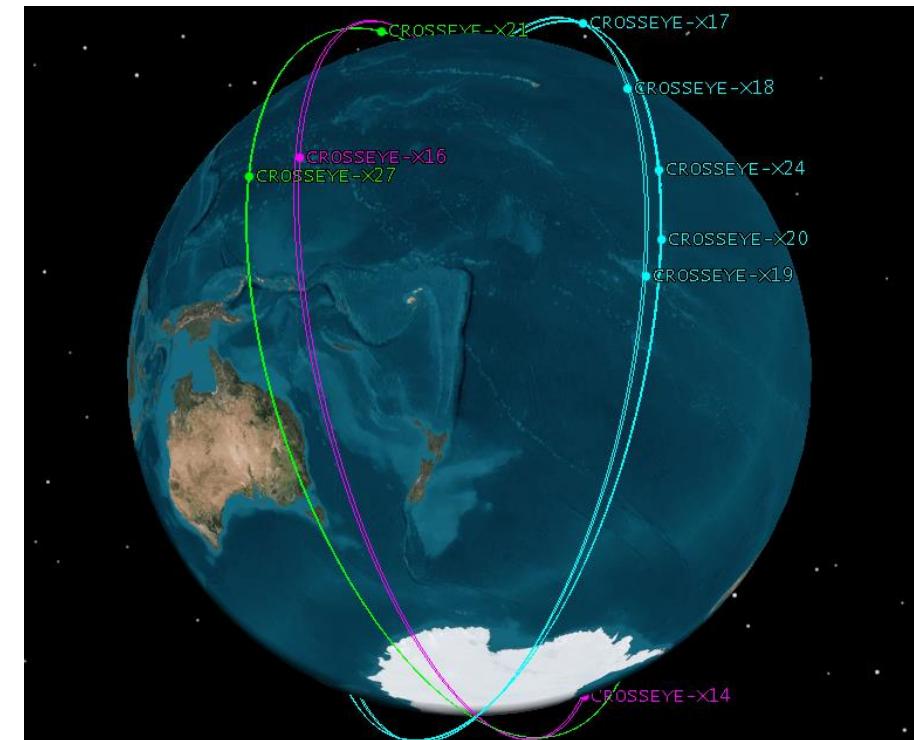


ICEYE



$\Delta\Omega, \Delta\nu, \Delta e$
→

CROSSEYE



LTAN

10:00 PM | 1:15 AM | 9:30 PM

ALTITUDE

490 ÷ 520 Km

INC

97.40 ÷ 97.55 °



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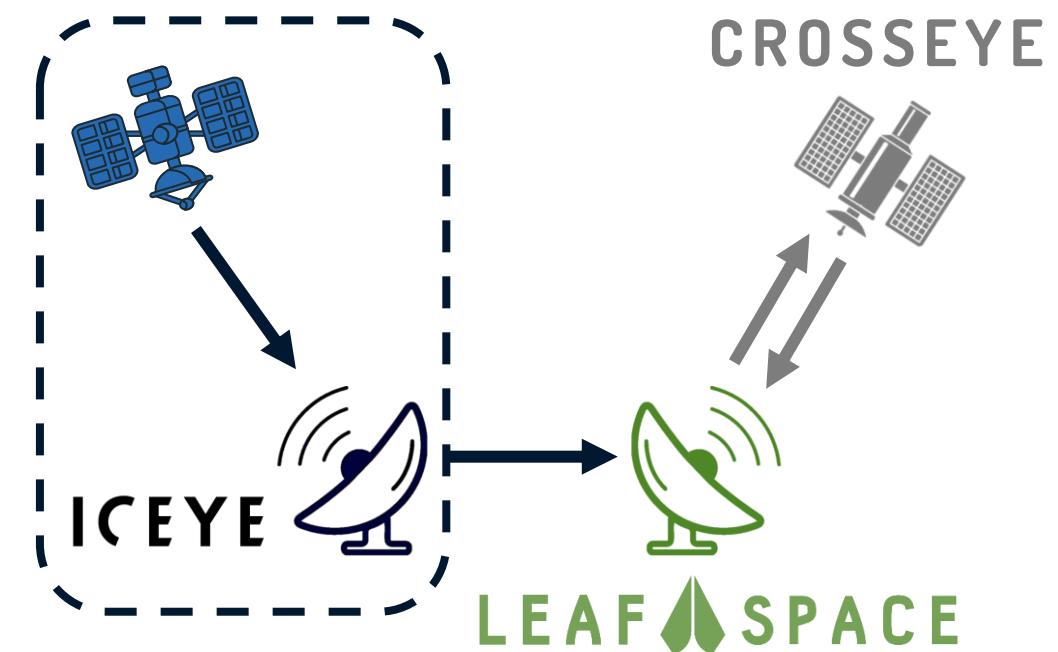
Ground Segment



ACTIVE
PLANNED
IN ACTIVATION



- 11 of 17 active Leaf Space ground stations placed at middle latitudes
- Link between the two missions at ground segment level





Plastic detection requirements

- 20 m minimum resolution
- VNIR, SWIR bands to compute FDI, NDVI, FAI indexes

6U CubeSat Standard compatibility

- Mass and Power constraints

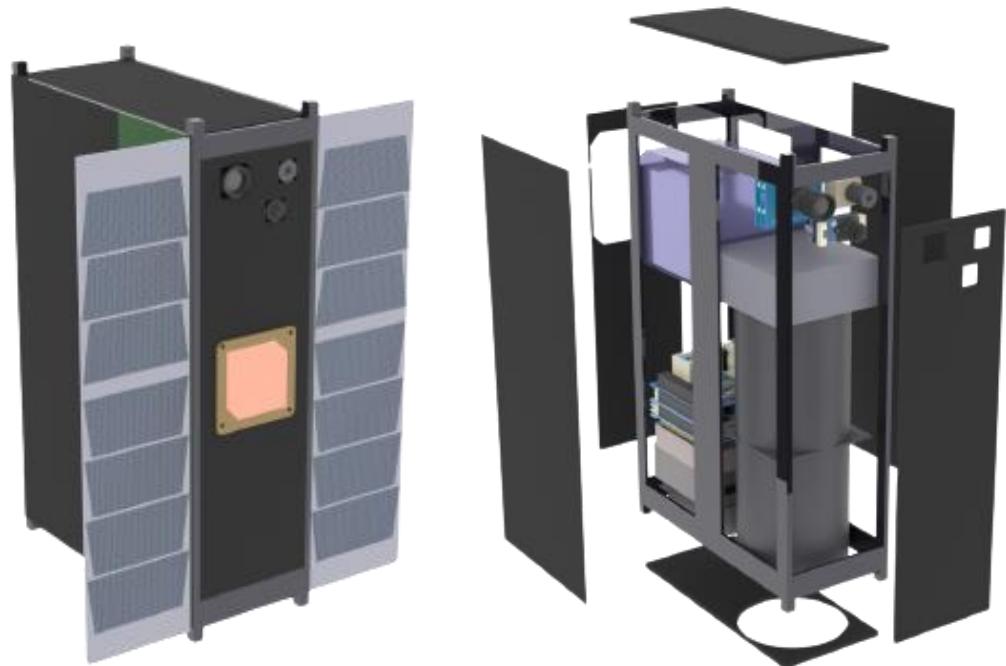


Custom electro-optical payload

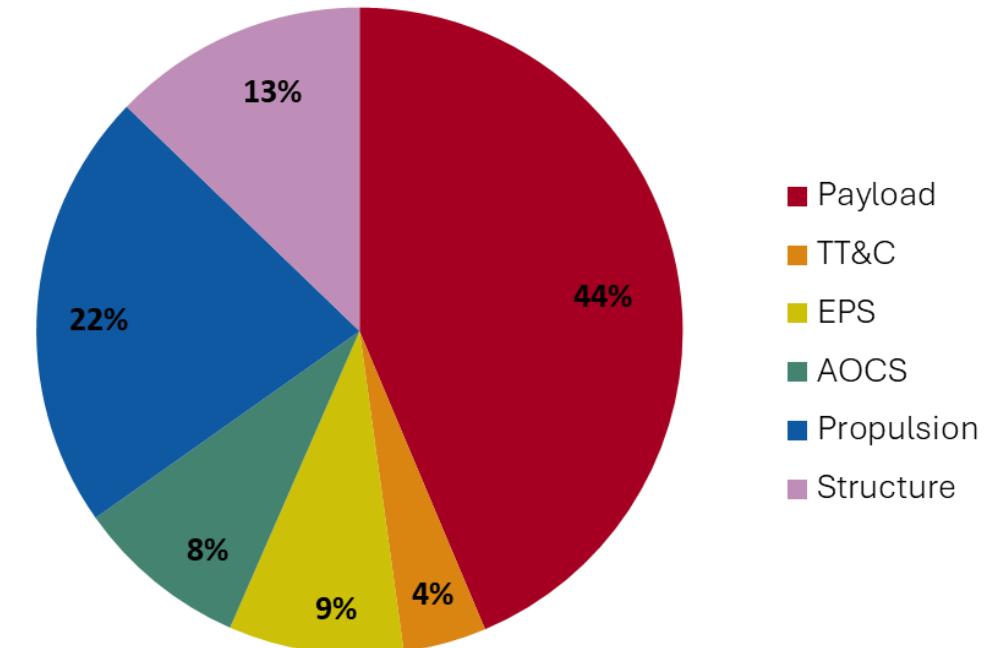
	VNIR	SWIR
Focal length (mm)	400	400
Aperture (mm)	96.0	96.0
F/#	4.17	4.17
FOV across track (deg)	1.76	2.20
Swath width (km)	16.0	20.0
Ground sampling distance (m)	15.6	9.80
MTF @32.5 lin/mm	0.66	0.66
Number of pixel (H x V)	1024 x 25	2048 x 1
Pixel size (μm)	12 x 12	7.5 x 7.5
Number of bands	5	1
Pixel depth (bits per pixel)	8	8
Mass (kg)	4.09	
Volume (mm^3)	1.5×10^6 (< 2U)	
Data rate (Mbps)	473	
Power consumption (Standby-On) (W)	1.00 – 35.0	



Preliminary design shows the compatibility with a standard 6U CubeSat platform



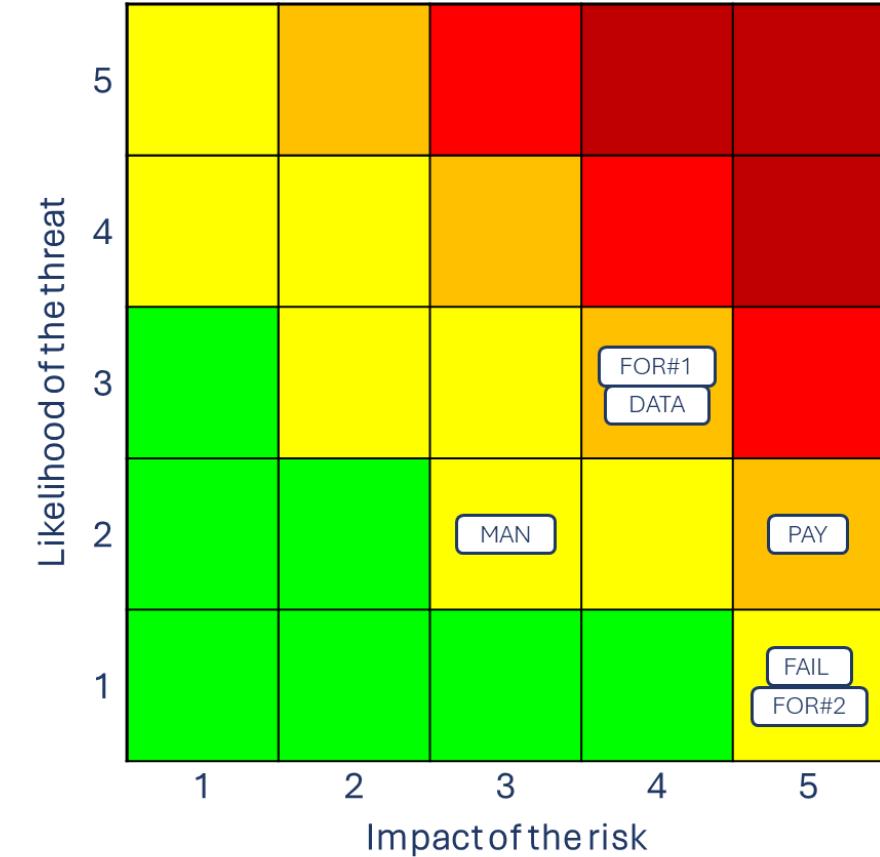
Mass Budget



TOTAL MASS	10.9 kg
TOTAL AVERAGE POWER CONSUMPTION	7.82 W



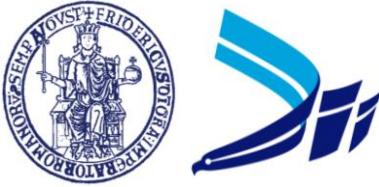
Risk	Description	L	I
PAY	Custom payload not feasible or integrable	2	5
FOR#1	Pendulum formation with ICEYE not reached	3	4
FOR#2	Collision risk	1	5
DATA	EO/SAR database building technique not implementable	3	4
FAIL	Not mature subsystems parts cause unexpected failures	1	5
MAN	Lack of handover, schedule delay, loss of information	2	3





Conclusions

- CROSSEYE platform design feasible integrating COTS components except for the payload
- Design easily adaptable to other SAR-equipped platforms
- Incremental strategy of CROSSEYE mission to widen the quantity and quality of collected data
- Capability to build a database tailored to fit the customer's demands (i.e., wildfire, coastal erosion, plastics)
- Contribution to plastic litter detection from space, promoting sustainability and furthering the understanding of Earth's ecosystem.



Conclusions

Thank you for the attention!

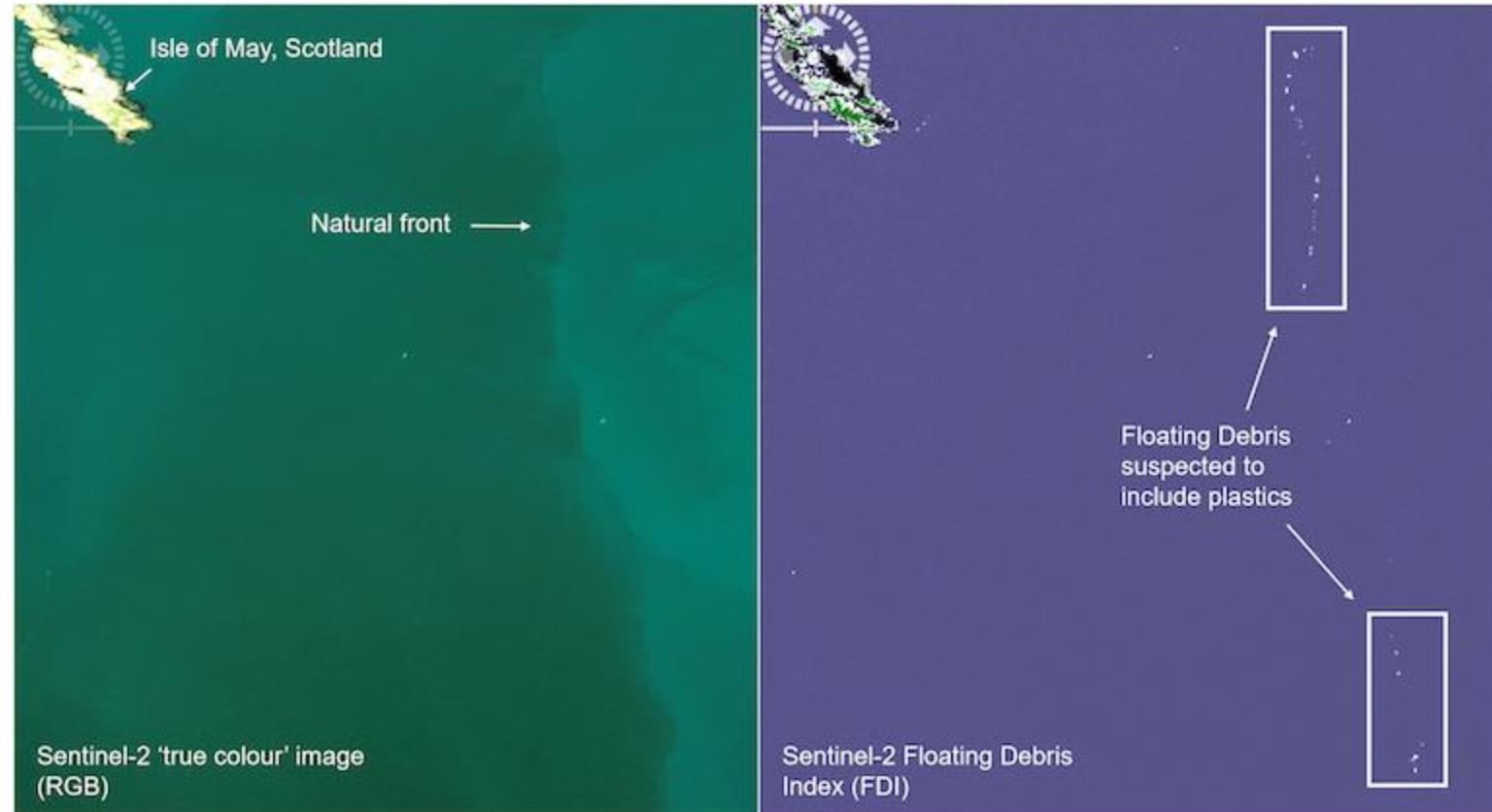
Q&A



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EO PLASTIC DETECTION

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Satellite imagery showing plastic pollution off the coast of Scotland. Image by Lauren Biermann



Mission Timeline

